Sequence Models

Jordan Boyd-Graber

University of Maryland

RNNs

Slides adapted from Jon Hewitt

Log-linear Language Models

Equation:

$$P(w \mid c) = \frac{\exp(\sum_{i} \lambda_{i} f_{i}(w, c))}{\sum_{w'} \exp(\sum_{i} \lambda_{i} f_{i}(w', c))}$$
(1)

where:

- $P(w \mid c)$ is the probability of word w given context c,
- $f_i(w,c)$ is a feature function representing some property of the word w and context c.
- λ_i is the (learned) weight of the corresponding feature.

Examples of Features:

- Presence of specific words in the context: $f_1(w, c) = 1$ if a particular word appears in c.
- Word length: $f_2(w, c) = \text{len}(w)$.
- Part of Speech: $f_3(w, c) = 1$ if w is a noun.

Bigram Language Model as a Log-Linear Model

Objective: Predict next word w = bageling given previous word c = go. **Log-Linear Model Equation:**

$$P(w \mid c) = \frac{\exp(\sum_{i} \lambda_{i} f_{i}(w, c))}{\sum_{w'} \exp(\sum_{i} \lambda_{i} f_{i}(w', c))}$$

Example Features:

- $f_1(w, c) = 1(c = \text{go}, w = \text{bageling})$
- $f_2(c) = 1(c = go)$
- $f_3(w,c) = 1(c = go, w = to)$

Weights:

- $\lambda_1 = 2.5$
- $\lambda_2 = -10.0$
- $\lambda_3 = 0.5$

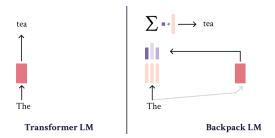
Prediction:

$$P(\text{bageling } | \text{go}) = \frac{\exp(2.5 - 10)}{\exp(-7.5) + \exp(3.0) + \exp(1.5)}$$
(2)

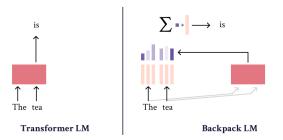
Normalizing over all possible next words.

Backpack Language Models

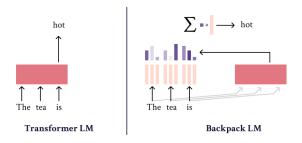
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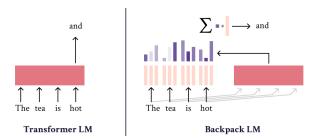
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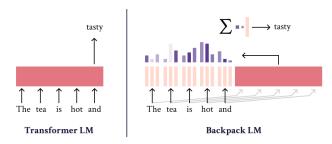
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Backpack Language Models

John Hewitt John Thickstun Christopher D. Manning Percy Liang
Department of Computer Science, Stanford University
{johnhew,jthickstun,manning,pliang}@cs.stanford.edu



But we're not talking about transformers today!

- However, general structure of Backpack Models is fairly simple
- Next time, we can reuse this framework to explain the transformer
- Shows the effect of non-linear context

Equation 1: Given input $x_1 \dots x_n$, sense vectors for the sequence:

$$C(x) = \{C(x)_1, \dots, C(x)_k\}$$

Equation 2: Weighted sum of sense vectors:

$$o_i = \sum_{j=1}^n \sum_{\ell=1}^k \alpha_{\ell,i,j} C(x_j)_{\ell}$$

$$p(y \mid o_{1:n}) = \operatorname{softmax}(E(o_{1:n}))$$

- $C(x)_1$ are sense vectors: e.g., a different vector for "dog" that barks and "dog" you serve on a bun.
- $\alpha_{i\,i}^\ell$ contextualization weights: which sense is relevant.
- $o_{1:n}$ is new representation for tokens
- That becomes input to predict next word through loglinear E

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Compare and Contrast

Traditional Feature-based Loglinear Models

- Dimension of features is gigantic (but sparse)
- · Fitting those weights is hard
- Very interpretable

Backpack Models

- Less interpretable than features
- More interpretable than RNN
- Comparable to GPT

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Example: Sense and Sentimentabilities

$$\mathbf{x} = \begin{pmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

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$$\mathbf{x} = \begin{pmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \end{pmatrix} \leftarrow \begin{array}{l} \text{Positive Sentiment} \\ \text{Negative Sentiment} \\ \text{Skateboarding Context} \\ \text{Health Context} \end{array}$$

Sentence: "That trick was sick"

that	trick	was	sick
$C(that)_0$	$C(trick)_0$	$C(was)_0$	$C(sick)_0$
$\begin{pmatrix} 0 & 0 & 0 & 0 \end{pmatrix}$	$\begin{pmatrix} 0 & 0 & 1 & 0 \end{pmatrix}$	$\begin{pmatrix} 0 & 0 & 0 & 0 \end{pmatrix}$	$\begin{pmatrix} 1 & 0 & 1 & 0 \end{pmatrix}$
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- Each word has two sense vectors: $C(x_i)_1$ and $C(x_i)_2$.
- "that" and "was" have zero vectors for both senses.
- "trick" has a non-zero vector for C(trick)₁ at the third position (evokes scateboarding), while the second vector is zero.
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Definition of $\alpha_{\ell,i,j}$:

$$\alpha_{\ell,i,j} = \begin{cases} \frac{C(\mathbf{x}_j)_{\ell+2}}{C(\mathbf{x}_j)_2 + C(\mathbf{x}_j)_3} & \text{if } j \neq i \\ 0 & \text{if } j = i \end{cases}$$
 (3)

- The active sense
- The resulting representation for word at index i
- The contribution from other words j
- This is +2 because there are only two senses, but the cue for which sense to use comes from the third and fourth index

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Which sense does "sick" take?

$$\mathbf{o}_i = \sum_{j=1}^n \sum_{\ell=1}^k \alpha_{\ell,i,j} C(\mathbf{x}_j)_{\ell}$$
 (5)

Given the feature vectors:

$$C(\operatorname{trick})_0 = \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix}, \quad C(\operatorname{sick})_0 = \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix}, \quad C(\operatorname{sick})_1 = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 1 \end{pmatrix}$$

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$$\mathbf{o}_{3} = \frac{C(\mathsf{trick})_{0}[2]}{C(\mathsf{trick})_{0}[2] + C(\mathsf{trick})_{0}[3]} \begin{pmatrix} 1\\0\\1\\0 \end{pmatrix} + \frac{C(\mathsf{trick})_{0}[3]}{C(\mathsf{trick})_{0}[2] + C(\mathsf{trick})_{0}[3]} \begin{pmatrix} 1\\0\\1\\0 \end{pmatrix}$$
(6)

(7)

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$$\mathbf{o}_{3} = \frac{1}{1+0} \begin{pmatrix} 1\\0\\1\\0 \end{pmatrix} + \frac{0}{1+0} \begin{pmatrix} 0\\1\\0\\1 \end{pmatrix} \tag{6}$$

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Wrap-up, Next time

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 - RNNs: linear evolution
 - Backpack models: selecting representations
- Next:
 - Attention: Scanning over entire sentence
 - Multiple representations: Transformer heads

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