





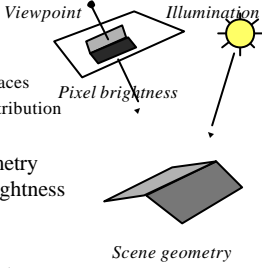
Perception of Shape from Shading

- Continuous image brightness variation due to shape variations is called *shading*
- Our perception of shape depends on shading
- Circular region on left is perceived as a flat disk
- Circular region on right has a varying brightness and is perceived as a sphere

From Image to Shape


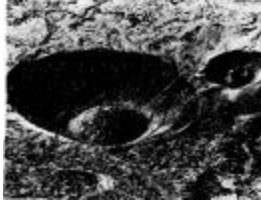
- Four main factors
 - Geometry of the scene
 - Reflectance of the visible surfaces
 - Illumination direction and distribution
 - Viewpoint
- Can we *compute* scene geometry from distribution of pixel brightness in scene image?
 - Only in very simple situations
 - Too many unknowns in general



Viewpoint, Illumination, Pixel brightness, Scene geometry

How Do We Do It?

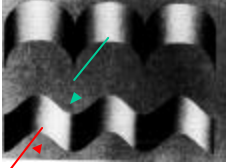
- Humans have to make assumptions about illumination: bump (left) is perceived as hole (right) when upside down

Illumination direction is unknown. It is assumed to come from above

Does Shading Play a Central Role?

- Contour plays a more important role
 - Variations in intensity are same on both shapes
 - Upper region is perceived as composed of three cylindrical pieces illuminated from above
 - Lower region is perceived as sinusoidal, illuminated from one side
 - Note the ambiguities of the surface perceptions, depending on assumed illumination direction

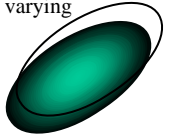


2 possible illumination hypotheses

Psychophysics

(Perception of Solid Shape from Shading, Mingolla & Todd, 1986)

- What assumptions do people make about surface reflectance?
- Is an estimate of illumination direction necessary?
- Stimuli: Shaded ellipsoids with varying
 - Elongations
 - Directions of light source
 - Reflectance
 - Cast shadows
- Test: *judge direction of light and surface orientations at discrete points*



Results

- Task is hard: errors 15 to 20 degrees
- No effect of glossiness, no Lambertian surface assumption
- No correlation between judgement of light directions and shape
 - No prior estimate of light direction
- Poor discrimination between elongated and rounded ellipsoids
 - Qualitative information

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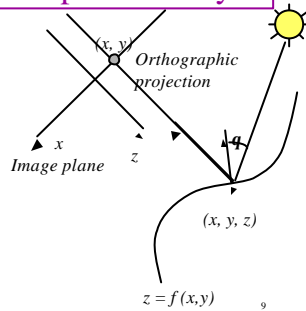
Human Shading Interpretation

- Is it metric or ordinal?
 - Metric: depth
 - Ordinal: depth order
- Answer:
 - Ordinal, qualitative
 - Magnitude of shading gradient is not important

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Quantitative Shape Recovery

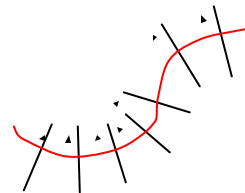
- Orthographic projection
- We have gray levels at pixels (x, y)
- We want to recover the orientations of the normals at points (x, y, z)
- By integration, we want to obtain $z = f(x, y)$



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From Normals to Surface Shape

- Fit a surface that is locally perpendicular to the normals

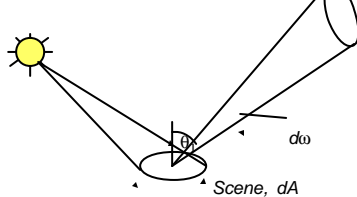


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Review: Radiance

- Radiance $L(\theta_1)$ is power emitted per unit area (flux) into a cone having unit solid angle
 - Area used is foreshortened area in direction \mathbf{q}_1

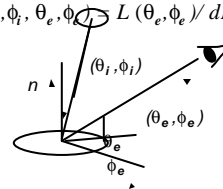
$$L(\theta_1) = d^2P / (dA \cos \theta_1 d\omega), \text{ in } W/m^2/sr$$



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Review: Reflectance

- Reflection is characterized by reflectance
- Reflectance is ratio radiance/irradiance
- Described by a function called Bidirectional Reflectance Distribution Function BRDF
- $BRDF = f(\theta_i, \phi_i, \theta_e, \phi_e) = L(\theta_e, \phi_e) / dE(\theta_i, \phi_i)$



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Review: Lambertian Surfaces

- If BRDF is a constant K , surface is called a Lambertian surface
- $dE = L' \cos \theta_0 d\omega = k L' \cos \theta_0$
- $L = K dE = K_1 L' \cos \theta_0$

- Radiance is same in all directions and is proportional to $\cos \theta_0$

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Pixel Brightness and Scene Brightness

$$\frac{da \cos \mathbf{a}}{(f / \cos \mathbf{a})^2} = \frac{dA \cos \mathbf{q}}{(Z / \cos \mathbf{a})^2} \Rightarrow \frac{dA}{da} = \frac{\cos \mathbf{a}}{\cos \mathbf{q}} \left(\frac{Z}{f} \right)^2$$

$$dP = L dA \Omega \cos \mathbf{q} \Rightarrow dP = L dA \frac{p}{4} \left(\frac{D}{Z} \right)^2 \cos^3 \mathbf{a} \cos \mathbf{q}$$

$$E = \frac{dP}{da} = L \frac{dA}{da} \frac{p}{4} \left(\frac{D}{Z} \right)^2 \cos^3 \mathbf{a} \cos \mathbf{q} \Rightarrow E = \frac{p}{4} \left(\frac{D}{f} \right)^2 \cos^4 \mathbf{a} L$$

$E = k L$

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Simple Radiometric Modeling

- Pixel Brightness is proportional to radiance of corresponding scene patch
- Radiance of scene patch is independent of viewpoint
- Radiance of scene patch is proportional to cosine of angle between normal to patch and direction of illumination source
- Therefore pixel brightness is proportional to cosine of angle between normal to patch and direction of illumination source

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Normals to $z = f(x, y)$

- We intersect surface $z=f(x,y)$ with red plane and blue plane
- We find tangents to red curve and blue curve
- We write that normal is perpendicular to 2 tangents and is in direction of cross-product

- Red tangent $(1, 0, \partial f / \partial x)$
- Blue tangent $(0, 1, \partial f / \partial y)$
- Normal $(\partial f / \partial x, \partial f / \partial y, -1)$

Gradient Space

- Orientations of normal $(\partial f / \partial x, \partial f / \partial y, -1)$ can be represented by 2 parameters

$$p = \partial f / \partial x$$

$$q = \partial f / \partial y$$

- The components p and q are called the gradient space coordinates of the normal
- Any direction (a, b, c) can be represented by $(-a/c, -b/c, -1)$, and by a point with 2 components $(p = -a/c, q = -b/c)$ in the same 2D gradient space
- Example: direction of light source can be written $(p_s, q_s)^T$

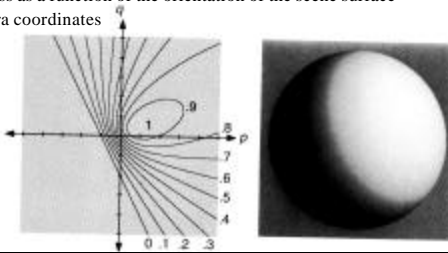
Geometric Interpretation of Gradient Space

- A direction (a, b, c) can be represented by a point on the plane $Z = -1$ by constructing the intersection between the vector of same direction (drawn from the origin) and the plane

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Reflectance Map

- A reflectance map is a 2D lookup table that gives the pixel brightness as a function of the orientation of the scene surface in camera coordinates



Reflectance Map for Point Light Source and Lambertian Surface

- Pixel brightness at pixel (x, y) is proportional to cosine of angle between normal to patch and direction of illumination source

$$I(x, y) = k \cos(\mathbf{q}) = k \frac{(p_s, q_s, -1) \cdot (p, q, -1)}{\sqrt{p_s^2 + q_s^2 + 1} \sqrt{p^2 + q^2 + 1}}$$

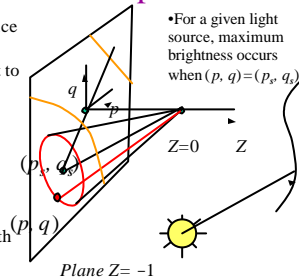
$$I(x, y)/k = k' = \frac{p_s p + q_s q + 1}{\sqrt{p_s^2 + q_s^2 + 1} \sqrt{p^2 + q^2 + 1}}$$

- For a given pixel brightness, the locus of possible normals (p, q) in gradient space is a conic

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Locus of Iso-Brightness in Reflectance Map

- Surface normals that produce a given brightness are at a constant angle with respect to direction of illumination
- The directions belong to a cone
- The locus corresponding to each brightness in the reflectance map is the intersection of the cone with the plane $Z = -1$



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Reflectance Map Obtained by Calibration Object

- A sphere can be used as a calibration object
 - Find distance of pixel to center of sphere
 - If distance < radius, compute direction of normal to sphere surface, and (p, q) for pixel
 - At position (p, q) of reflectance map, store pixel value
- Useful only for scene material similar to sphere

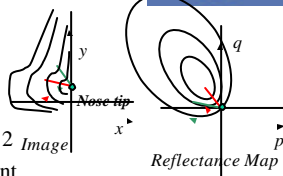
$$p = \frac{x}{\sqrt{R^2 - x^2 - y^2}}$$

$$q = \frac{y}{\sqrt{R^2 - x^2 - y^2}}$$

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Using Reflectance Map to Find Normals

- We are on the image at a pixel where we know the direction of the normal, a point in the reflectance map
- Find Gradient 1 at pixel
- Find Gradient 2 at reflectance map point
- Move in image by Gradient 2
- Then the corresponding point in reflectance map is moved by Gradient 1



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Proof

- Gradient 1 in image = $\left(\frac{\partial I}{\partial x}, \frac{\partial I}{\partial y} \right)$
- Gradient 2 in reflectance map = $\left(\frac{\partial R}{\partial p}, \frac{\partial R}{\partial q} \right)$
- If $(dx, dy) = \text{Gradient 2}$, $dp = \frac{\partial p}{\partial x} dx + \frac{\partial p}{\partial y} dy = \frac{\partial p}{\partial x} dx + \frac{\partial q}{\partial x} dy$
 $dq = \frac{\partial R}{\partial p} \frac{\partial p}{\partial x} + \frac{\partial R}{\partial q} \frac{\partial q}{\partial x} = \frac{\partial I}{\partial x}$
 $dq = \frac{\partial R}{\partial p} \frac{\partial p}{\partial y} + \frac{\partial R}{\partial q} \frac{\partial q}{\partial y} = \frac{\partial I}{\partial y}$
- Then $(dp, dq) = \text{Gradient 1}$

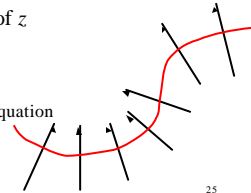
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From Normals to Surface Shape

- Step by step $z(x + dx, y + dy) = z(x, y) + dz$
 $dz = \frac{\partial z}{\partial x} dx + \frac{\partial z}{\partial y} dy = p dx + q dy$
- Global least square formulation leads to expression for Laplacian of z

$$\Delta z = \frac{\partial^2 p}{\partial x^2} + \frac{\partial^2 q}{\partial y^2}$$

- Second order differential equation



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Application to Face Recognition (Zhao and Chellappa)

- Appearance of faces changes when viewing and lighting directions change
- Face databases use front views and frontal lighting
- If we can reconstruct 3D face shape, we can convert any face image into a front-view with frontal lighting and compare to the database faces
- Use shape from shading and symmetry of face
- Or assume generic shape, but varying albedo, and remove unknown albedo by using symmetry of face

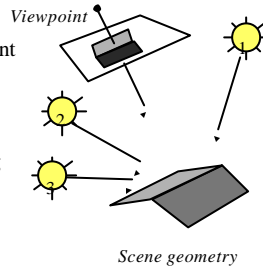


Synthetic faces for
4 angles and
2 illuminations

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Photometric Stereo

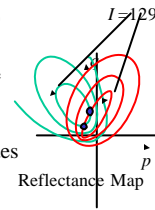
- Move light source at different known positions to obtain different shadings of object with unknown geometry
- Find geometry from shading information



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Photometric Stereo

- Different illumination conditions lead to different reflectance maps
 - Each reflectance map can be computed if we know position of point light source
- Intersection of 2 iso-brightness contours corresponding to same brightness provides 2 possible normal directions for pixels having that brightness value
- Three maps give unambiguous normals for each pixel



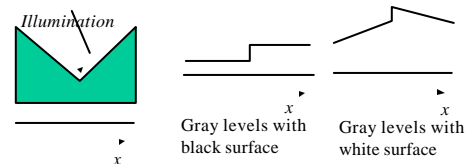
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Assumptions of Shape from Shading

- Surfaces with constant albedo
- Orthographic projection
- Distant point sources
- Absence of cast shadows
- **Insignificance of secondary illumination**
 - This one is a real problem: inter-reflections are everywhere

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Inter-Reflections



- Accurate computation of shape from shading is unlikely to succeed in real world
- Shape from shading may be used as a complementary process
- Edges are more reliable indicators of shape

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The Real World

- Diffuse light sources (overcast sky)
- Interreflections between surfaces generate secondary light sources
- Surfaces have varying light absorption (albedo)
- Surface reflections range from Lambertian to specular
- Surfaces cast shadows on each other

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Conclusions

- Accurate computation of shape from shading is unlikely to succeed in the real world
- Edges are more reliable indicators of shape
- Shape from shading may be used as a complementary process in combination with shape inference from edges
- There is still a lot of research activity in this area, so it is useful to have an idea of the terminology and the techniques (reflectance map, etc.)

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References

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- "SFS Based View Synthesis for Robust Face Recognition", W.Y. Zhao and R. Chellappa, www.cfar.umd.edu/~wyzhao

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