

# Frameworks

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Introduction

Slides adapted from Chris Dyer, Yoav Goldberg, Graham Neubig

# Neural Nets and Language

## Language

Discrete, structured (graphs, trees)

Big challenge: writing code that translates between the {discrete-structured, continuous} regimes

## Neural-Nets

Continuous: poor native support for structure

## Why not do it yourself?

- Hard to compare with existing models
- Obscures difference between model and optimization
- Debugging has to be custom-built
- Hard to tweak model

# Outline

- Computation graphs (general)
- Neural Nets in PyTorch
- Full example

# Computation Graphs

Expression

$\vec{x}$

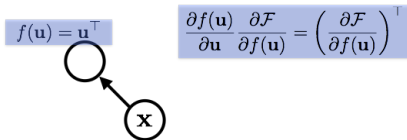
graph:



# Computation Graphs

## Expression

$\vec{x}^\top$



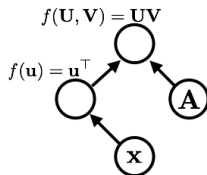
- Edge: function argument / data dependency
- A node with an incoming edge is a function  $F \equiv f(u)$  edge's tail node
- A node computes its value and the value of its derivative w.r.t each argument (edge) times a derivative  $\frac{\partial f}{\partial u}$

# Computation Graphs

Expression

$$\vec{x}^T A$$

graph:



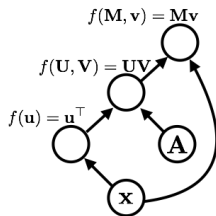
Functions can be nullary, unary, binary, . . . n-ary. Often they are unary or binary.

# Computation Graphs

Expression

$$\vec{x}^T A x$$

graph:



Computation graphs are (usually) directed and acyclic

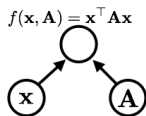
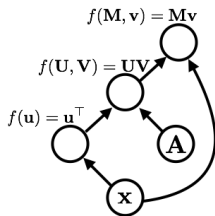


# Computation Graphs

Expression

$$\vec{x}^\top A x$$

graph:



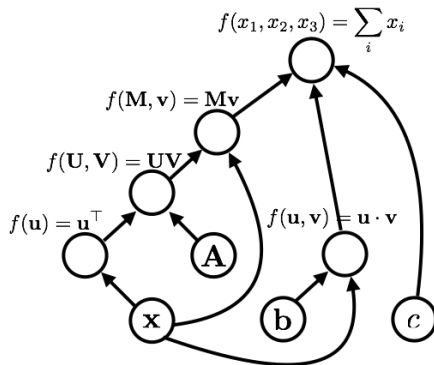
$$\frac{\partial f(\mathbf{x}, \mathbf{A})}{\partial \mathbf{x}} = (\mathbf{A}^\top + \mathbf{A})\mathbf{x}$$
$$\frac{\partial f(\mathbf{x}, \mathbf{A})}{\partial \mathbf{A}} = \mathbf{x}\mathbf{x}^\top$$

# Computation Graphs

Expression

$$\vec{x}^T A x + b \cdot \vec{x} + c$$

graph:

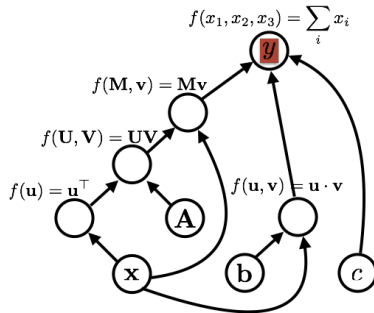


# Computation Graphs

## Expression

$$y = \vec{x}^\top A x + b \cdot \vec{x} + c$$

graph:

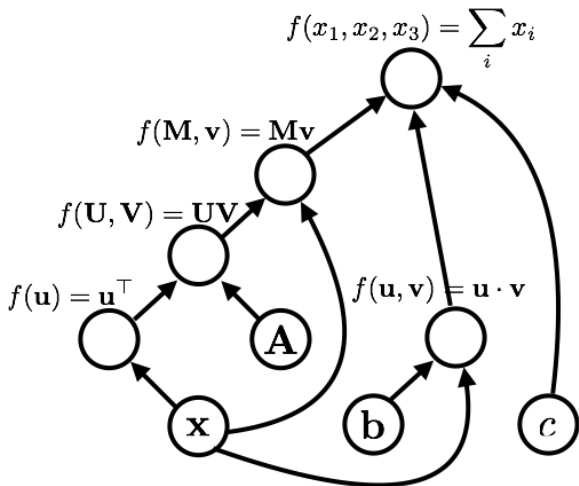


Variable names label nodes

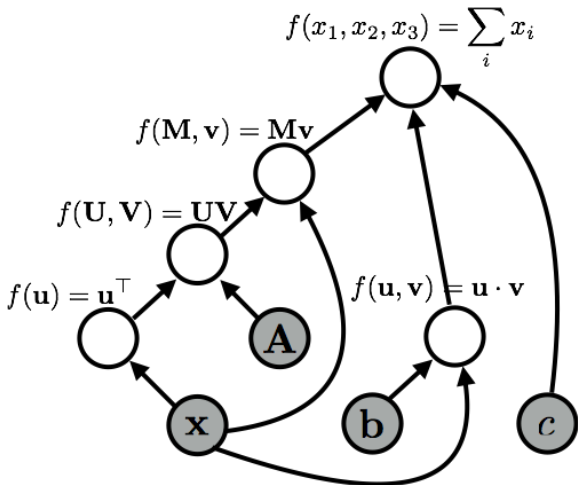
# Algorithms

- Graph construction
- Forward propagation
  - ▶ Loop over nodes in topological order
  - ▶ Compute the value of the node given its inputs
  - ▶ Given my inputs, make a prediction (i.e. “error” vs. “target output”)
- Backward propagation
  - ▶ Loop over the nodes in reverse topological order, starting with goal node
  - ▶ Compute derivatives of final goal node value wrt each edge’s tail node
  - ▶ How does the output change with small change to inputs?

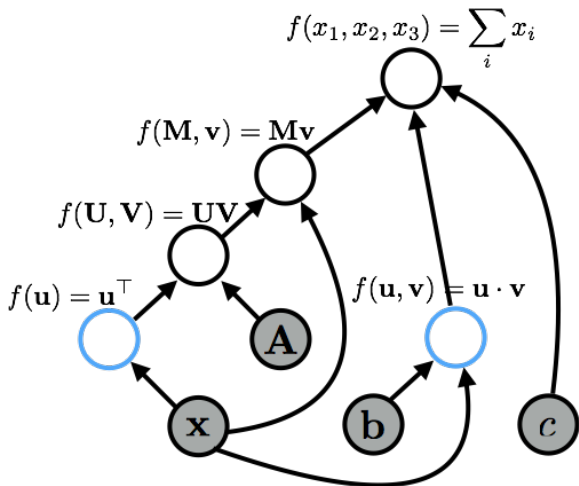
## Forward Propagation



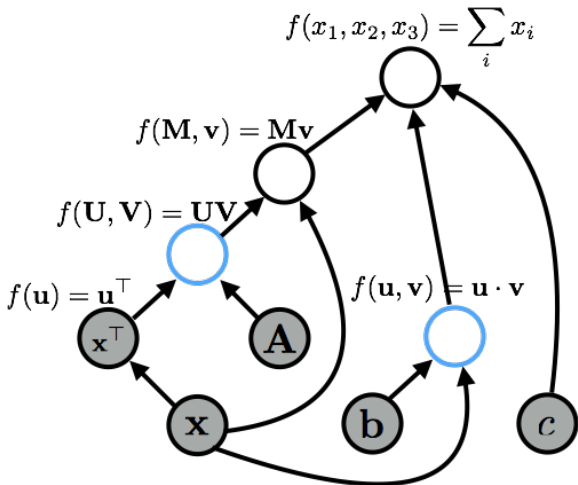
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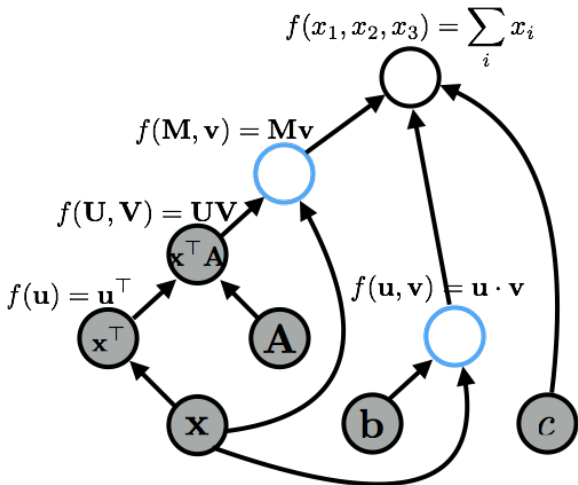


## Forward Propagation

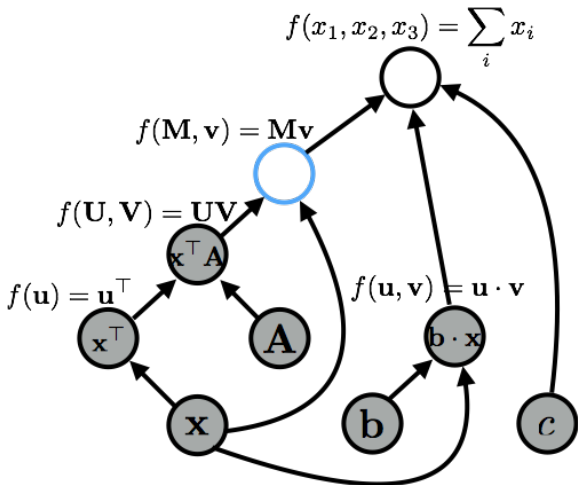




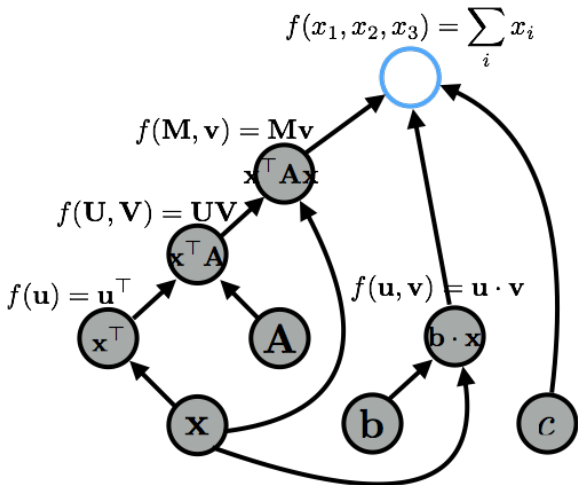
## Forward Propagation



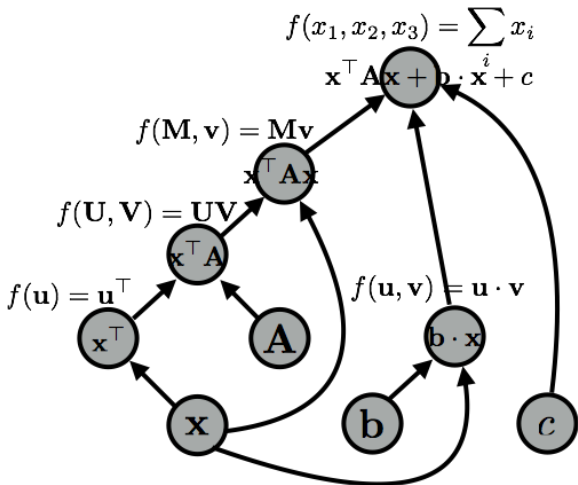
## Forward Propagation



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## Forward Propagation



# Constructing Graphs

## Static declaration

- Define architecture, run data through
- PROS: Optimization, hardware support
- CONS: Structured data ugly, graph language

Theano, Tensorflow

## Dynamic declaration

- Graph implicit with data
- PROS: Native language, interleave construction/evaluation
- CONS: Slower, computation can be wasted

Chainer, Dynet, PyTorch

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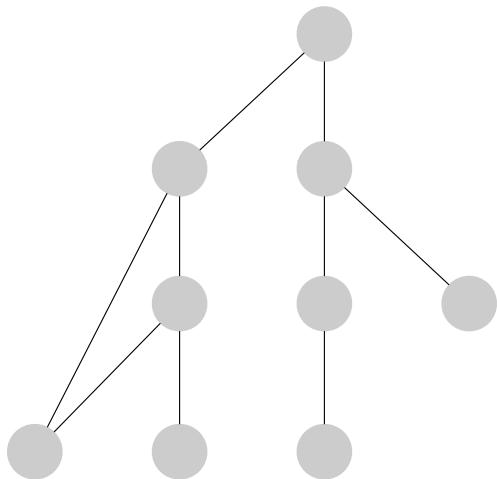
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## Advantage of Dynamic Declaration

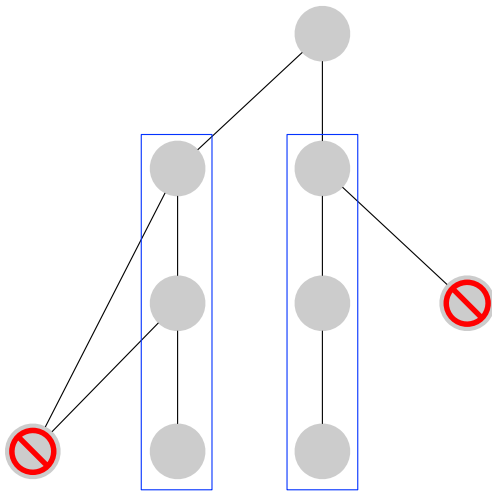


Only get computation graph at runtime



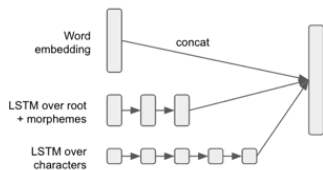


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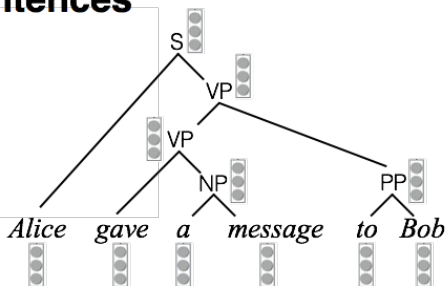


Parallelize on different physical computations

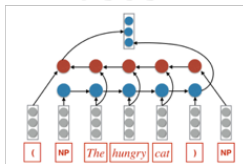
## Words



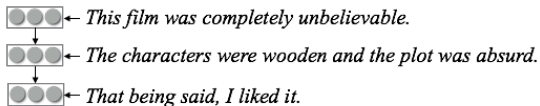
## Sentences



## Phrases



## Documents



Language is Hierarchical

# Dynamic Hierarchy in Language

- Language is hierarchical
  - ▶ Graph should reflect this reality
  - ▶ Traditional flow-control best for processing
- Combinatorial algorithms (e.g., dynamic programming)
- Exploit independencies to compute over a large space of operations tractably

# PyTorch

- Torch: Facebook's deep learning framework
- Nice, but written in Lua (C backend)
- Optimized to run computations on GPU
- Mature, industry-supported framework

# Why GPU?



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