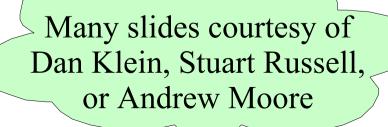
# Utility

#### Hal Daumé III

- Computer Science University of Maryland
- me@hal3.name
- CS 421: Introduction to Artificial Intelligence
- 16 Feb 2012





Hal Daumé III (me@hal3.name)

CS421: Intro to AI

### Announcements

► P1

- Due Tuesday (late days until Thursday)
- Will post solution Friday morning
- P2 up
  - By end of today, you can complete it
  - Feel free to use anything from (y)our P1 or your P2

# Hal's Lottery

- You pay \$M to enter my lottery
- I put \$1 in the pot
- Now, I start flipping fair coins
  - If the coin = heads, I double the pot
  - If the coin = tails, the game ends and you get the pot
- How much would you pay (\$M) to enter my lottery?

> Note, \$1 = 30 minutes on P2

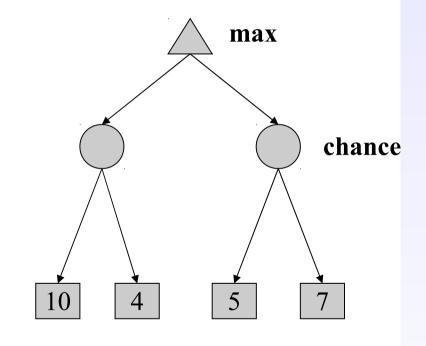
#### http://u.hal3.name/ic.pl?lottery

#### Where we are and where we're going

- Where we've been:
  - Single agent, known world, known rewards
  - Multi-agent, known world, known rewards
- > Where we're going:
  - Stochastic, known world, known rewards (Markov Decision Processes)
  - Stochastic, ~known world, unknown rewards (Reinforcement Learning)

### **Expectimax Search Trees**

- What if we don't know what the result of an action will be? E.g.,
  - In solitaire, next card is unknown
  - In minesweeper, mine locations
  - In pacman, the ghosts act randomly
- Can do expectimax search
  - Chance nodes, like min nodes, except the outcome is uncertain
  - Calculate expected utilities
  - Max nodes as in minimax search
  - Chance nodes take average (expectation) of value of children
- Later, we'll learn how to formalize the underlying problem as a Markov Decision Process



## **Maximum Expected Utility**

- Why should we average utilities? Why not minimax?
- Principle of maximum expected utility: an agent should chose the action which maximizes its expected utility, given its knowledge
- General principle for decision making
- Often taken as the definition of rationality
- We'll see this idea over and over in this course!
- Let's decompress this definition...

## **Reminder: Probabilities**

- A random variable is an event whose outcome is unknown
- A probability distribution is an assignment of weights to outcomes
- Example: traffic on freeway?
  - Random variable: T = whether there's traffic
  - Outcomes: T in {none, light, heavy}
  - Distribution: P(T=none) = 0.25, P(T=light) = 0.55, P(T=heavy) = 0.20
- Some laws of probability (more later):
  - Probabilities are always non-negative
  - Probabilities over all possible outcomes sum to one
- > As we get more evidence, probabilities may change:
  - P(T=heavy) = 0.20, P(T=heavy | Hour=8am) = 0.60
  - We'll talk about methods for reasoning about probabilities later

## What are Probabilities?

#### Objectivist / frequentist answer:

- Averages over repeated experiments
- E.g. empirically estimating P(rain) from historical observation
- Assertion about how future experiments will go (in the limit)
- New evidence changes the reference class
- Makes one think of *inherently random* events, like rolling dice

#### Subjectivist / Bayesian answer:

- Degrees of belief about unobserved variables
- E.g. an agent's belief that it's raining, given the temperature
- E.g. pacman's belief that the ghost will turn left, given the state
- Often *learn* probabilities from past experiences (more later)
- New evidence updates beliefs (more later)

## **Dutch Books**

Horse	Odds	Price
1	Even	\$100
2	3 to 1	\$50
3	4 to 1	\$40
4	9 to 1	\$20

- If your internal beliefs don't obey the rules of probability:
  - I can construct a Dutch book
  - ==> I can take infinite amounts of money from you!

## **Uncertainty Everywhere**

#### Not just for games of chance!

- I'm sniffling: am I sick?
- Email contains "FREE!": is it spam?
- Tooth hurts: have cavity?
- 60 min enough to get to the airport?
- Robot rotated wheel three times, how far did it advance?
- Safe to cross street? (Look both ways!)
- Why can a random variable have uncertainty?
  - Inherently random process (dice, etc)
  - Insufficient or weak evidence
  - Ignorance of underlying processes
  - Unmodeled variables
  - The world's just noisy!
- Compare to fuzzy logic, which has degrees of truth, or rather than just degrees of belief

## **Reminder: Expectations**

- Often a quantity of interest depends on a random variable
- The expected value of a function is its average output, weighted by a given distribution over inputs
- Example: How late if I leave 60 min before my flight?
  - Lateness is a function of traffic: L(none) = -10, L(light) = -5, L(heavy) = 15
  - What is my expected lateness?
    - Need to specify some belief over T to weight the outcomes
    - Say P(T) = {none: 2/5, light: 2/5, heavy: 1/5}
    - The expected lateness:

$$E_{P(T)}[L(T)] = \frac{2}{5} \times (-10) + \frac{2}{5} \times (-5) + \frac{1}{5} \times (15)$$

P(none)L(none)+P(light)L(light)+P(heavy)L(heavy)

#### **Reminder: Expectations**

Real valued functions of random variables:

$$f: X \to R$$

Expectation of a function of a random variable

$$E_{P(X)}[f(X)] = \sum_{x} f(x)P(x)$$

Example: Expected value of a fair die roll

## **Two Envelopes Problem**

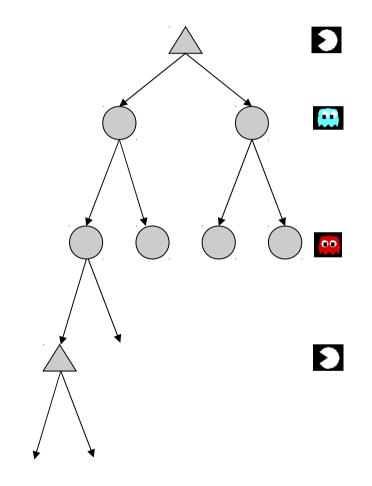
- One envelope contains \$100, the other \$200
- Pick an envelope, then I'll let you switch if you want
- Pick an envelope A
- ▶ p(A is \$100) = p(A is \$200) = 0.5
- if A is \$100, then other contains \$200
   if A is \$200, then other contains \$100
- So other contains 2\*A with p=0.5 and A/2 with p=0.5
- E[money in other] =
- So you should swap...
- ➤ and swap...
- and swap...

#### Utilities

- Utilities are functions from outcomes (states of the world) to real numbers that describe an agent's preferences
- Where do utilities come from?
  - In a game, may be simple (+1/-1)
  - Utilities summarize the agent's goals
  - Theorem: any set of preferences between outcomes can be summarized as a utility function (provided the preferences meet certain conditions)
- In general, we hard-wire utilities and let actions emerge (why don't we let agents decide their own utilities?)
- More on utilities soon…

## **Expectimax Search**

- In expectimax search, we have a probabilistic model of how the opponent (or environment) will behave in any state
  - Model could be a simple uniform distribution (roll a die)
  - Model could be sophisticated and require a great deal of computation
  - We have a node for every outcome out of our control: opponent or environment
  - The model might say that adversarial actions are likely!
- For now, assume for any state we magically have a distribution to assign probabilities to opponent actions / environment outcomes



Having a probabilistic belief about an agent's action does not mean that agent is flipping any coins!

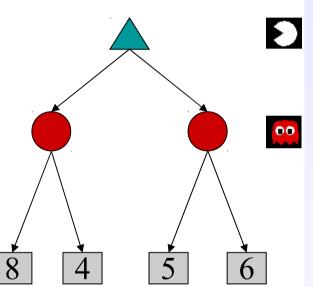
Hal Daumé III (me@hal3.name)

CS421: Intro to Al

#### **Expectimax Pseudocode**

def value(s)
 if s is a max node return maxValue(s)
 if s is an exp node return expValue(s)
 if s is a terminal node return evaluation(s)

```
def maxValue(s)
  values = [value(s') for s' in successors(s)]
  return max(values)
```

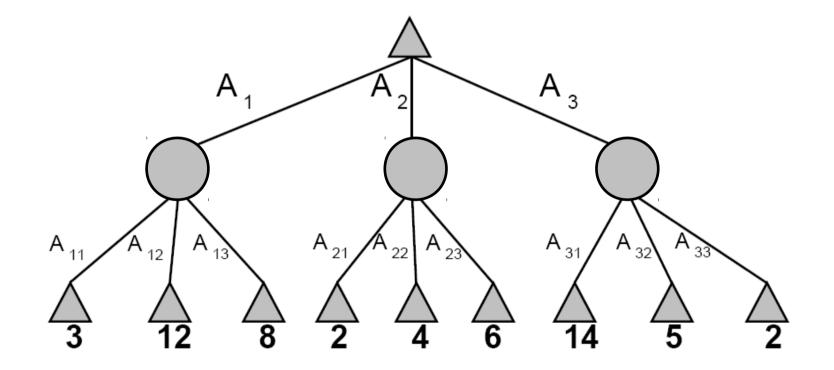


def expValue(s)
 values = [value(s') for s' in successors(s)]
 weights = [probability(s, s') for s' in successors(s)]
 return expectation(values, weights)

# **Expectimax for Pacman**

- Notice that we've gotten away from thinking that the ghosts are trying to minimize pacman's score
- Instead, they are now a part of the environment
- Pacman has a belief (distribution) over how they will act
- Quiz: Can we see minimax as a special case of expectimax?
- Quiz: what would pacman's computation look like if we assumed that the ghosts were doing 1-ply minimax and taking the result 80% of the time, otherwise moving randomly?
- If you take this further, you end up calculating belief distributions over your opponents' belief distributions over your belief distributions, etc...
  - Can get unmanageable very quickly!

#### **Expectimax Pruning?**



### **Expectimax Evaluation**

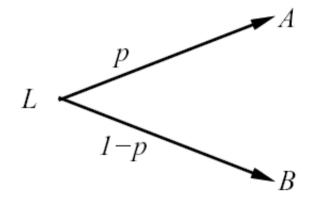
- For minimax search, evaluation function insensitive to monotonic transformations
  - We just want better states to have higher evaluations (get the ordering right)
- For expectimax, we need the magnitudes to be meaningful as well
  - E.g. must know whether a 50% / 50% lottery between A and B is better than 100% chance of C
  - 100 or -10 vs 0 is different than 10 or -100 vs 0

#### **Preferences**

- An agent chooses among:
  - > Prizes: A, B, etc.
  - Lotteries: situations with uncertain prizes

$$L = [p, A; (1 - p), B]$$

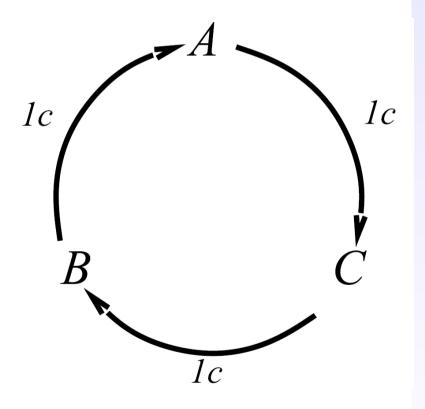
Notation:



- $A \succ B$  A preferred over B
- $A \sim B$  indifference between A and B
- $A \succeq B$  B not preferred over A

## **Rational Preferences**

- We want some constraints on preferences before we call them rational
- For example: an agent with intransitive preferences can be induced to give away all its money
  - If B > C, then an agent with C would pay (say) 1 cent to get B
  - If A > B, then an agent with B would pay (say) 1 cent to get A
  - If C > A, then an agent with A would pay (say) 1 cent to get C



#### **Rational Preferences**

Preferences of a rational agent must obey constraints.

The axioms of rationality:

Orderability  $(A \succ B) \lor (B \succ A) \lor (A \sim B)$ Transitivity  $(A \succ B) \land (B \succ C) \Rightarrow (A \succ C)$ Continuity  $A \succ B \succ C \Rightarrow \exists p \ [p, A; \ 1-p, C] \sim B$ Substitutability  $A \sim B \Rightarrow [p, A; 1-p, C] \sim [p, B; 1-p, C]$ Monotonicity  $A \succ B \Rightarrow$  $(p \ge q \Leftrightarrow [p, A; 1-p, B] \succeq [q, A; 1-q, B])$ 

Theorem: Rational preferences imply behavior describable as maximization of expected utility

## **MEU Principle**

- > Theorem:
  - [Ramsey, 1931; von Neumann & Morgenstern, 1944]
  - Given any preferences satisfying these constraints, there exists a real-valued function U such that:

 $U(A) \ge U(B) \iff A \succeq B$  $U([p_1, S_1; \dots; p_n, S_n]) = \sum_i p_i U(S_i)$ 

Maximum expected likelihood (MEU) principle:

- Choose the action that maximizes expected utility
- Note: an agent can be entirely rational (consistent with MEU) without ever representing or manipulating utilities and probabilities
- E.g., a lookup table for perfect tictactoe, reflex vacuum cleaner

## Pascal's Wager (d 1662)

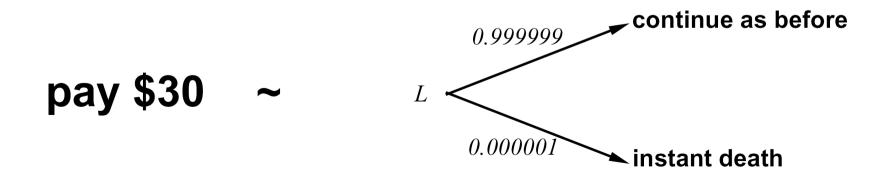
A "proof" that it is a good idea to believe in God

	God	God Doesn't
	Exists	Exist
Believe	+infinity	-10
Don't Believe	-infinity	0

- Problems with this argument (mathematically)?
- Problems with this argument (theologically)?
- Exists in many cultures:
  - Islam: al-Juwayni (d 1085)
  - Sanskrit: Sarasamuccaya

### **Human Utilities**

- Utilities map states to real numbers. Which numbers?
- Standard approach to assessment of human utilities:
  - Compare a state A to a standard lottery L<sub>p</sub> between
    - ``best possible prize" u<sub>+</sub> with probability p
    - ``worst possible catastrophe" u\_ with probability 1-p
  - Adjust lottery probability p until A ~ L<sub>p</sub>
  - Resulting p is a utility in [0,1]



## **Utility Scales**

- > Normalized utilities:  $u_{+} = 1.0$ ,  $u_{-} = 0.0$
- Micromorts: one-millionth chance of death, useful for paying to reduce product risks, etc.
- QALYs: quality-adjusted life years, useful for medical decisions involving substantial risk
- Note: behavior is invariant under positive linear transformation  $U'(x) = k_1 U(x) + k_2 \quad \text{where } k_1 > 0$

With deterministic prizes only (no lottery choices), only ordinal utility can be determined, i.e., total order on prizes

#### **Example: Insurance**

- Consider the lottery [0.5,\$1000; 0.5,\$0]
  - What is its expected monetary value? (\$500)
  - What is its certainty equivalent?
    - Monetary value acceptable in lieu of lottery
    - http://u.hal3.name/ic.pl?q=insurance
  - Difference is the insurance premium

## Hal's Lottery, revisited

Friendly game	\$100	\$4.28	
Millionaire	\$1,000,000	\$10.95	
Billionaire	\$1,000,000,000	\$15.93	
Bill Gates (2008)	\$58,000,000,000	\$18.84	
US GDP (2007)	\$13.8 trillion	\$22.79	
World GDP (2007)	\$54.3 trillion	\$23.77	
Googolaire	\$10^100	\$166.50 <sup>e</sup>	p

- How much would you pay (\$M) to enter? E[payoff] = (1/2) 1 + (1/4) 2 + (1/8) 4 + (1/16) 8 + ... = (1/2) + (1/2) + (1/2) + (1/2) + ... = infinity!
- > Why weren't we willing to pay \$1m to enter?

# Money

- Money does not behave as a utility function
- Given a lottery L:
  - Define expected monetary value EMV(L)
  - Usually U(L) < U(EMV(L))</p>
  - I.e., people are risk-averse
- Utility curve: for what probability p am I indifferent between:
  - A prize x
  - A lottery [p,\$M; (1-p),\$0] for large M?
- Typical empirical data, extrapolated with risk-prone behavior:

\_\_\_

#### **Example: Human Rationality?**

- Famous example of Allais (1953)
  - A: [0.8,\$4k; 0.2,\$0]
    B: [1.0,\$3k; 0.0,\$0]
  - C: [0.2,\$4k; 0.8,\$0]
  - D: [0.25,\$3k; 0.75,\$0]

#### http://u.hal3.name/ic.pl?q=allais

## **Reinforcement Learning**

#### > [DEMOS]

#### Basic idea:

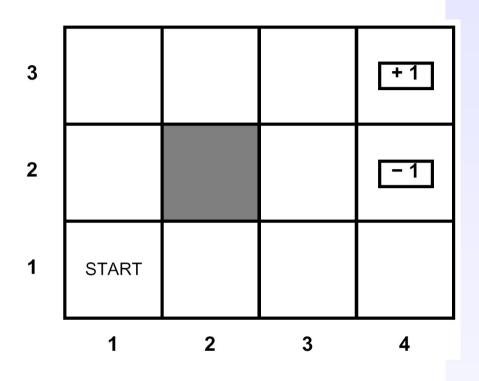
- Receive feedback in the form of rewards
- Agent's utility is defined by the reward function
- Must learn to act so as to maximize expected rewards
- Change the rewards, change the learned behavior

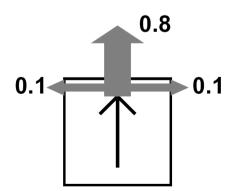
#### Examples:

- Playing a game, reward at the end for winning / losing
- Vacuuming a house, reward for each piece of dirt picked up
- Automated taxi, reward for each passenger delivered

## **Markov Decision Processes**

- An MDP is defined by:
  - > A set of states  $s \in S$
  - A set of actions  $a \in A$
  - A transition function T(s,a,s')
    - Prob that a from s leads to s'
    - i.e., P(s' | s,a)
    - Also called the model
  - A reward function R(s, a, s')
    - Sometimes just R(s) or R(s')
  - A start state (or distribution)
  - Maybe a terminal state
- MDPs are a family of nondeterministic search problems
  - Reinforcement learning: MDPs where we don't know the transition or reward functions





CS421: Intro to Al