

# Sequence Models

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Slides adapted from Richard Socher

#### Language models

- Language models answer the question: How likely is a string of English words good English?
- Autocomplete on phones and websearch
- Creating English-looking documents
- Very common in machine translation systems
  - Help with reordering / style

 $p_{\text{Im}}$ (the house is small) >  $p_{\text{Im}}$ (small the is house)

Help with word choice

 $p_{lm}(l \text{ am going home}) > p_{lm}(l \text{ am going house})$ 

#### **N-Gram Language Models**

- Given: a string of English words  $W = w_1, w_2, w_3, ..., w_n$
- Question: what is p(W)?
- Sparse data: Many good English sentences will not have been seen before
- $\rightarrow$  Decomposing p(W) using the chain rule:

 $p(w_1, w_2, w_3, ..., w_n) =$  $p(w_1) p(w_2|w_1) p(w_3|w_1, w_2) \dots p(w_n|w_1, w_2, ..., w_{n-1})$ 

(not much gained yet,  $p(w_n|w_1, w_2, ..., w_{n-1})$  is equally sparse)

### Markov Chain

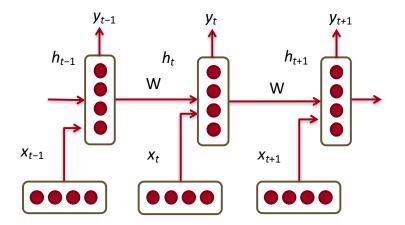
### Markov independence assumption:

- only previous history matters
- limited memory: only last k words are included in history (older words less relevant)
- $\rightarrow k$ th order Markov model
- For instance 2-gram language model:

 $p(w_1, w_2, w_3, ..., w_n) \simeq p(w_1) p(w_2|w_1) p(w_3|w_2) ... p(w_n|w_{n-1})$ 

 What is conditioned on, here w<sub>i-1</sub> is called the history. Estimated from counts.

### **Recurrent Neural Networks**



- Condition on all previous words
- Hidden state at each time step

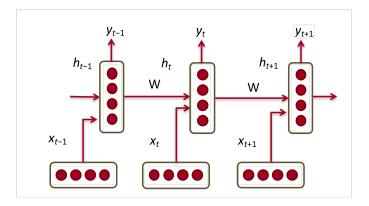
#### **RNN** parameters

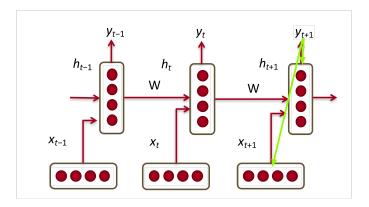
$$h_t = f(W^{(hh)}h_{t-1} + W^{(hx)}x_t)$$
(1)

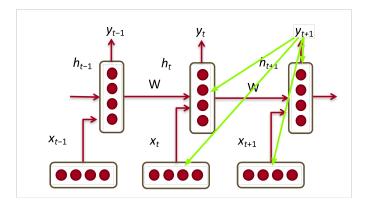
$$\hat{y}_t = \operatorname{softmax}(W^{(S)}h_t)$$
 (2)

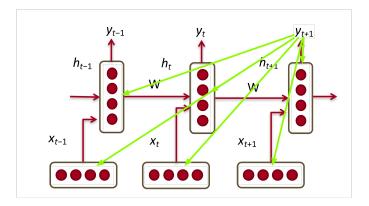
$$P(x_{t+1} = v_j | x_t, \dots x_1) = \hat{y}_{t,j}$$
(3)

- Learn parameter h<sub>0</sub> to initialize hidden layer
- *x<sub>t</sub>* is representation of input (e.g., word embedding)
- $\hat{y}$  is probability distribution over vocabulary









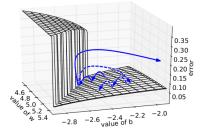
### Vanishing / Exploding Gradient

- Work out the math:
  - Define  $\beta_W / \beta_h$  as upper bound of norms of *W*, *h*
  - Bengio et al 1994: Partial derivative is  $(\beta_W \beta_h)^{t-k}$
  - This can be very small or very big
- If it's big, SGD jumps too far
- If it's small, we don't learn what we need: "Jane walked into the room. John walked in too. It was late in the day. Jane said hi to \_\_\_\_\_"

### **Gradient Clipping**

Algorithm 1 Pseudo-code for norm clipping the gradients whenever they explode

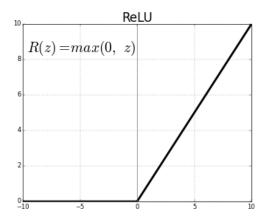
 $\begin{array}{l} \hat{\mathbf{g}} \leftarrow \frac{\partial \mathcal{E}}{\partial \theta} \\ \text{if } \| \hat{\mathbf{g}} \| \geq threshold \ \textbf{then} \\ \hat{\mathbf{g}} \leftarrow \frac{threshold}{\| \hat{\mathbf{g}} \|} \hat{\mathbf{g}} \\ \text{end if} \end{array}$ 



From Pascanu et al. 2013

- If they get too big, stop at boundary
- Prevents (dashed) values from jumping around (solid)

### **Fixing Vanishing Gradients**



- ReLU activation
- Initialize W to identity matrix

### **RNN Recap**

- Simple model
- Complicated training (but good toolkits available)
- Do we need to remember everything?