

Introduction to Machine Learning

Machine Learning: Jordan Boyd-Graber University of Maryland SUPPORT VECTOR MACHINES

Slides adapted from Tom Mitchell, Eric Xing, and Lauren Hannah

Roadmap

- Classification: machines labeling data for us
- Previously: naïve Bayes and logistic regression
- This time: SVMs
 - (another) example of linear classifier
 - State-of-the-art classification
 - Good theoretical properties

Thinking Geometrically

- Suppose you have two classes: vacations and sports
- Suppose you have four documents

Sports	Vacations
Doc ₁ : {ball, ball, ball, travel}	Doc ₃ : {travel, ball, travel}
Doc ₂ : {ball, ball}	Doc ₄ : {travel}

What does this look like in vector space?

Put the documents in vector space

Travel



Ball

Vector space representation of documents

- Each document is a vector, one component for each term.
- Terms are axes.
- High dimensionality: 10,000s of dimensions and more
- How can we do classification in this space?

Vector space classification

- As before, the training set is a set of documents, each labeled with its class.
- In vector space classification, this set corresponds to a labeled set of points or vectors in the vector space.
- Premise 1: Documents in the same class form a **contiguous region**.
- Premise 2: Documents from different classes don't overlap.
- We define lines, surfaces, hypersurfaces to divide regions.





Should the document * be assigned to China, UK or Kenya?



Find separators between the classes



Find separators between the classes



Based on these separators: * should be assigned to China



How do we find separators that do a good job at classifying new documents like \star ? – Main topic of today

Linear classifiers

- Definition:
 - A linear classifier computes a linear combination or weighted sum $\sum_i \beta_i x_i$ of the feature values.
 - Classification decision: $\sum_i \beta_i x_i > \beta_0$? (β_0 is our bias)
 - ... where β_0 (the threshold) is a parameter.
- We call this the **separator** or **decision boundary**.
- We find the separator based on training set.
- Methods for finding separator: logistic regression, naïve Bayes, linear SVM
- Assumption: The classes are **linearly separable**.

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- Before, we just talked about equations. What's the geometric intuition?



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 B x + B x + B x = B

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Naive Bayes and Logistic Regression as linear classifiers

Multinomial Naive Bayes is a linear classifier (in log space) defined by:

$$\sum_{i=1}^M \beta_i x_i = \beta_0$$

where $\beta_i = \log[\hat{P}(t_i|c)/\hat{P}(t_i|\bar{c})]$, $x_i =$ number of occurrences of t_i in d, and $\beta_0 = -\log[\hat{P}(c)/\hat{P}(\bar{c})]$. Here, the index i, $1 \le i \le M$, refers to terms of the vocabulary.

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Takeway

Naïve Bayes, logistic regression and SVM are all linear methods. They choose their hyperplanes based on different objectives: joint likelihood (NB), conditional likelihood (LR), and the margin (SVM).

Which hyperplane?



Which hyperplane?

- For linearly separable training sets: there are infinitely many separating hyperplanes.
- They all separate the training set perfectly
- ... but they behave differently on test data.
- Error rates on new data are low for some, high for others.
- How do we find a low-error separator?

- Machine-learning research in the last two decades has improved classifier effectiveness.
- New generation of state-of-the-art classifiers: support vector machines (SVMs), boosted decision trees, regularized logistic regression, neural networks, and random forests
- Applications to IR problems, particularly text classification

SVMs: A kind of large-margin classifier

Vector space based machine-learning method aiming to find a decision boundary between two classes that is maximally far from any point in the training data (possibly discounting some points as outliers or noise)

2-class training data



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- decision boundary →
 linear separator



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- linear separator position defined by support vectors



Why maximize the margin?

- Points near decision surface → uncertain classification decisions
- A classifier with a large margin is always confident
- Gives classification safety margin (measurement or variation)



Why maximize the margin?

- SVM classifier: large margin around decision boundary
- compare to decision hyperplane: place fat separator between classes
 - unique solution
- decreased memory capacity
- increased ability to correctly generalize to test data



Equation

Equation of a hyperplane

$$\vec{w} \cdot x_i + b = 0 \tag{1}$$

Distance of a point to hyperplane

$$\frac{|\vec{w} \cdot x_i + b|}{||\vec{w}||} \tag{2}$$

• The margin ho is given by

$$\rho \equiv \min_{(x,y)\in S} \frac{|\vec{w} \cdot x_i + b|}{||\vec{w}||} = \frac{1}{||\vec{w}||}$$
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• This is because for any point on the marginal hyperplane, $\vec{w} \cdot x + b = \pm 1$

Optimization Problem

We want to find a weight vector \vec{w} and bias b that optimize

$$\min_{\vec{w},b} \frac{1}{2} ||w||^2 \tag{4}$$

subject to $y_i(\vec{w} \cdot x_i + b) \ge 1, \forall i \in [1, m].$

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Next week: algorithm

Three Proofs that Suggest SVMs will Work

- Leave-one-out error
- VC Dimension
- Margin analysis

Leave One Out Error (sketch)

Leave one out error is the error by using one point as your test set (averaged over all such points).

$$\hat{R}_{LOO} = \frac{1}{m} \sum_{i=1}^{m} \mathbb{1} \left[h_{s - \{x_i\}} \neq y_i \right]$$
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This serves as an unbiased estimate of generalization error for samples of size m-1:

$$\mathbb{E}_{S \sim D^m} \left[\hat{R}_{LOO} \right] = \mathbb{E}_{S' \sim D^{m-1}} \left[R(h_{S'}) \right]$$
(6)

Leave One Out Error (sketch)

Let h_S be the hypothesis returned by SVMs for a separable sample *S*, and let $N_{SV}(S)$ be the number of support vectors that define h_S .

$$\mathbb{E}_{S \sim D^m} \left[R(h_s) \right] \le \mathbb{E}_{S \sim D^{m+1}} \left[\frac{N_{SV}(S)}{m+1} \right]$$
(7)

Consider the held out error for x_i .

- If x_i was not a support vector, the answer doesn't change.
- If x_i was a support vector, it could change the answer; this is when we can have an error.

There are $N_{SV}(S)$ support vectors and thus $N_{SV}(S)$ possible errors.

VC Dimension Argument

Remember discussion VC dimension for *d*-dimensional hyperplanes? That applies here:

$$R(h) \le \hat{R}(h) + \sqrt{\frac{2(d+1)\log\frac{\epsilon}{d+1}}{m}} + \sqrt{\frac{\log\frac{1}{\delta}}{2m}}$$
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But this is useless when *d* is large (e.g. for text).

Margin Theory

To see where SVMs really shine, consider the margin loss ρ :

$$\Phi_{\rho}(x) = \begin{cases} 0 & \text{if } \rho \leq x \\ 1 - \frac{x}{\rho} & \text{if } 0 \leq x \leq \rho \\ 1 & \text{if } x \leq 0 \end{cases}$$
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The fraction of the points in the training sample *S* that have been misclassified or classified with confidence less than ρ .

Generalization

For linear classifiers $H = \{x \mapsto w \cdot x : ||w|| \le \Lambda\}$ and data $X \in \{x : ||x|| \le r\}$. Fix $\rho > 0$ then with probability at least $1 - \delta$, for any $h \in H$,

$$R(h) \le \hat{R}_{\rho}(h) + 2\sqrt{\frac{r^2\Lambda^2}{\rho^2 m}} + \sqrt{\frac{\log\frac{1}{\delta}}{2m}}$$
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- Data-dependent: must be separable with a margin
- Fortunately, many data do have good margin properties
- SVMs can find good classifiers in those instances

- None?
- Very little?
- A fair amount?
- A huge amount

- None? Hand write rules or use active learning
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- A huge amount Doesn't matter, use whatever works

SVM extensions: What's next

- Finding solutions
- Slack variables: not perfect line
- Kernels: different geometries

